Interaction representation for time evolution of $\mathcal{H}(t) = \mathcal{H}_0 - b(t)B$:

$$\frac{dA}{dt} = \frac{\imath}{\hbar} [\mathcal{H}_0, A] \quad \Rightarrow \quad A(t) = e^{\imath \mathcal{H}_0 t/\hbar} A e^{-\imath \mathcal{H}_0 t/\hbar},
\frac{dB}{dt} = \frac{\imath}{\hbar} [\mathcal{H}_0, B] \quad \Rightarrow \quad B(t) = e^{\imath \mathcal{H}_0 t/\hbar} B e^{-\imath \mathcal{H}_0 t/\hbar},
\frac{d\rho}{dt} = -\frac{\imath}{\hbar} [-b(t)B, \rho] \quad \Rightarrow \quad \rho(t) = \rho_0 + \frac{\imath}{\hbar} \int_{-\infty}^t dt' b(t') [B(t'), \rho(t')].$$

Set
$$\rho(t) = \rho_0 + \rho_1(t)$$
 with $\rho_0 = Z_0^{-1} e^{-\beta \mathcal{H}_0}$.

Full response: $\langle A(t) \rangle - \langle A \rangle_0 = \text{Tr}\{\rho_1(t)A(t)\}$

Leading correction to ρ_0 : $\rho_1(t) \simeq \frac{i}{\hbar} \int_{-\infty}^t dt' b(t') [B(t'), \rho_0]$

Linear response:

$$\langle A(t) \rangle - \langle A \rangle_0 = \frac{\imath}{\hbar} \int_{-\infty}^t dt' b(t') \text{Tr}\{[B(t'), \rho_0] A(t)\}$$

$$= \frac{\imath}{\hbar} \int_{-\infty}^t dt' b(t') \text{Tr}\{\rho_0[A(t), B(t')]\}$$

$$= \frac{\imath}{\hbar} \int_{-\infty}^t dt' b(t') \langle [A(t), B(t')] \rangle_0.$$

Compare with definition of response function in [nln26].

Kubo formula:

$$\tilde{\chi}_{AB}(t-t') = \frac{\imath}{\hbar} \theta(t-t') \langle [A(t), B(t')] \rangle_0.$$

- Causality requirement is ensured by step function $\theta(t-t')$.
- Hermitian A, B imply Hermitian i[A, B]. Hence $\tilde{\chi}(t)$ is real.
- Linear response depends only on equilibrium quantities.
- Response function only depends on time difference t t'.

The Kubo formula establishes a general link between

- the dynamical properties of a many-body system at equilibrium,
- the dynamical response of that system to experimental probes.