[gex97] Inertia tensor from rotational kinetic energy of rigid body

Consider a rigid body in purely rotational motion with angular velocity ω about some instantaneous axis. The (instantaneous) kinetic energy can then be constructed from the expression,

$$K = \frac{1}{2} \sum_{\alpha} m_{\alpha} \left(\boldsymbol{\omega} \times \mathbf{r}_{\alpha} \right)^{2}, \tag{1}$$

where m_{α} are infinitesimal mass elements at positions \mathbf{r}_{α} in a coordinate system fixed to the rigid body with its origin on the axis of rotation. Extract from (1) the expression,

$$I_{ij} = \sum_{\alpha} m_{\alpha} \left[\delta_{ij} r_{\alpha}^2 - r_{\alpha i} r_{\alpha j} \right], \tag{2}$$

for the inertia tensor by transforming (1) into the form,

$$K = \frac{1}{2} \sum_{ij} I_{ij} \,\omega_i \omega_j. \tag{3}$$

Solution: